

Phase Transition of the 2-Choices Dynamics on Core-Periphery Networks

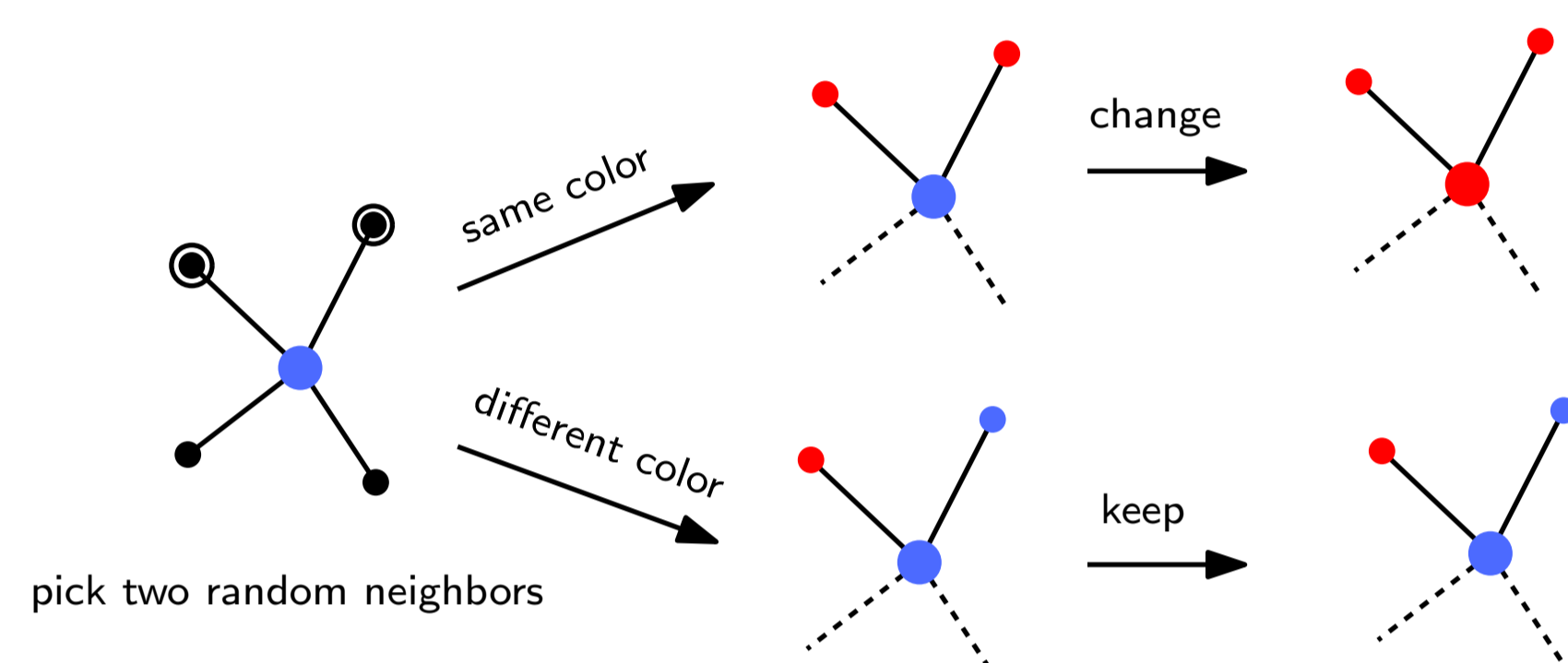
Emilio Cruciani and Emanuele Natale and André Nusser and Giacomo Scornavacca
Gran Sasso Science Institute and Max Planck Institute for Informatics and University of L'Aquila



2-Choices Dynamics

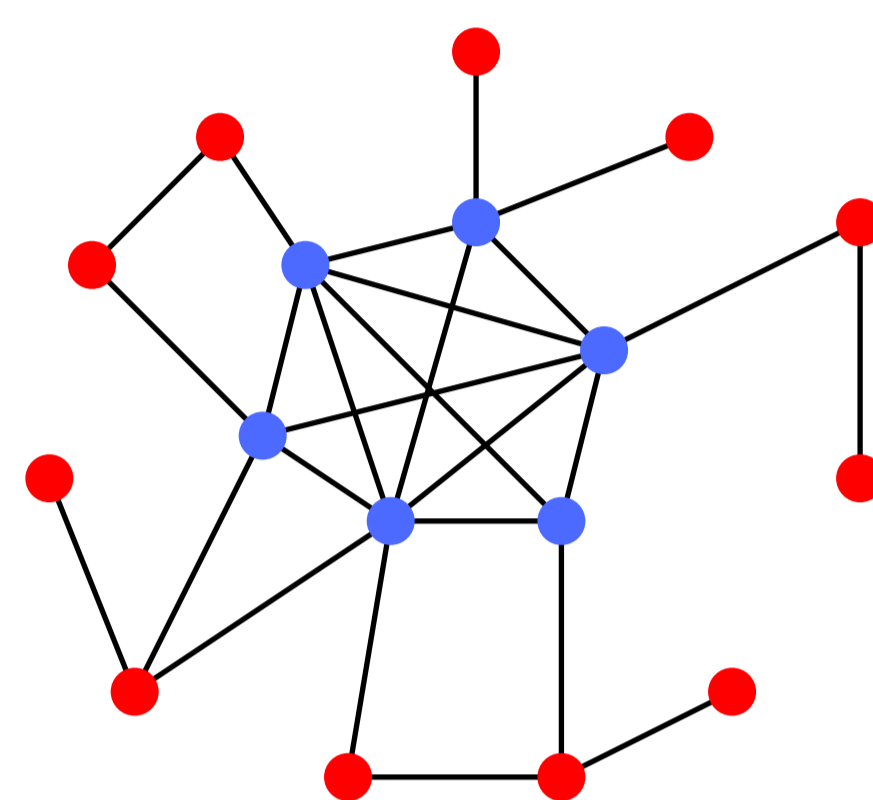
Given a graph $G = (V, E)$ and a coloring $V \rightarrow \{\text{red}, \text{blue}\}$, a **dynamics** is a process where in every synchronous round each node updates its color depending on its neighbors' colors according to a simple rule.

In the **2-Choices dynamics** the update rule is: *choose two random neighbors and if they have the same color, adopt it.*



Core-Periphery Network

A **core-periphery** network is a graph with a set \mathcal{C} of densely connected nodes (**the core**) and the rest of the nodes \mathcal{P} (**the periphery**) is loosely connected and dominated by the core.



We call $c_d = \frac{c(\mathcal{C}, \mathcal{P})}{c(\mathcal{P}, \mathcal{P})}$ the **dominance** and $c_r = \frac{c(\mathcal{C}, \mathcal{C})}{c(\mathcal{C}, \mathcal{P})}$ the **robustness**, where $c(A, B)$ is the number of cut edges between A and B .

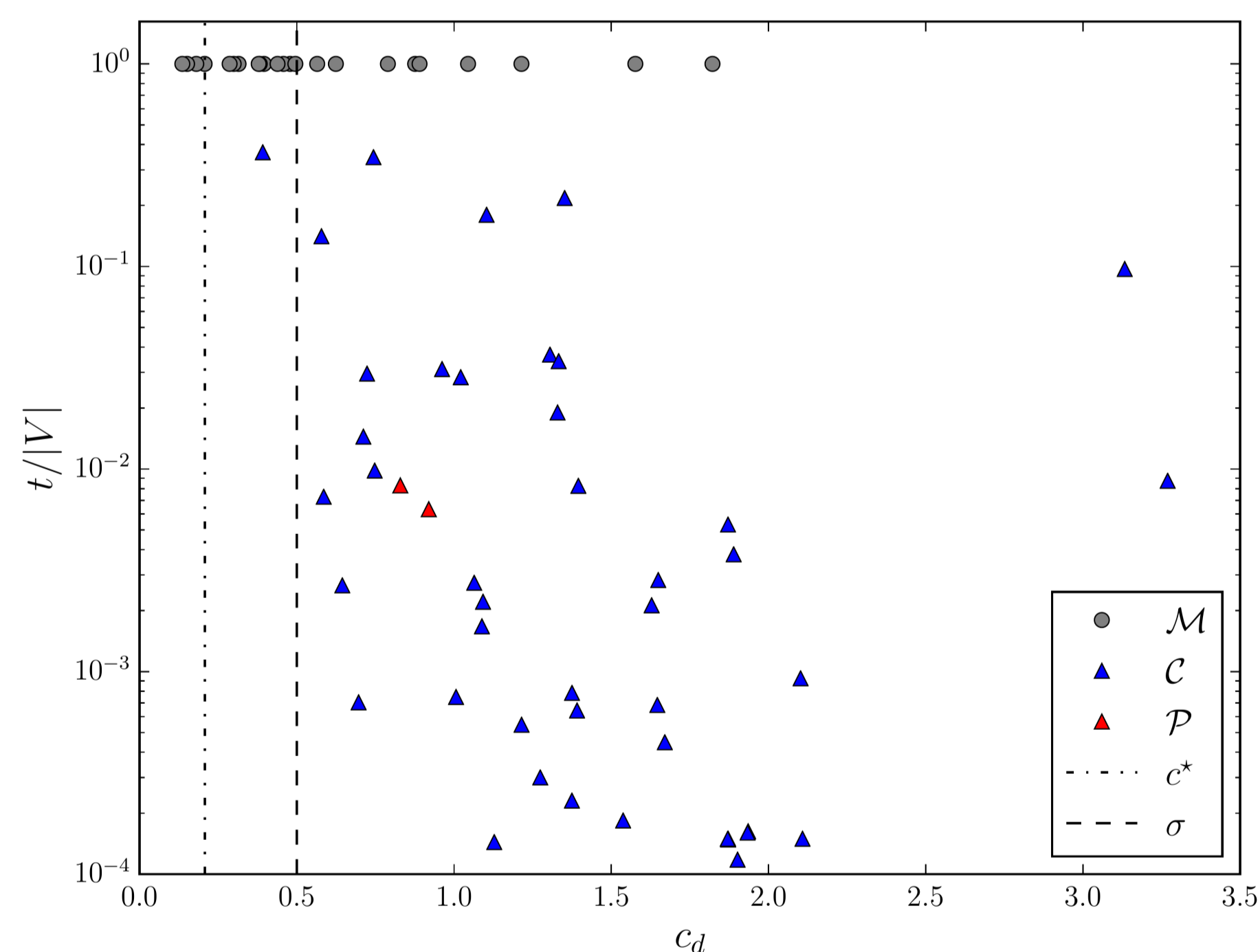
Main Result

When running the 2-Choices dynamics on core-periphery networks where the core is initially blue and the periphery is initially red, there exists a universal constant c^* such that

- if $c_d > c^*$ and c_r is large enough, then a configuration of **almost-consensus** on blue is reached in $\mathcal{O}(\log n)$ rounds with high probability
- if $c_d < c^*$, then a **metastable** phase takes place where most of the nodes retain their initial opinion for $n^{\omega(1)}$ rounds with high probability

Experimental Results

Tests conducted on **70 real-world networks**.



Metastability and almost-consensus of the experiments compared to the theoretical and empirical thresholds c^* and σ . In total, 86% of the runs are metastable when $c_d < \sigma$; and 81% of them lead to an almost-consensus if $c_d > \sigma$. (t = number of rounds until almost-consensus/metastability was declared; \mathcal{M} = metastability)

Selected Related Work

Two-choices dynamics: *The power of two choices in distributed voting.* Cooper, Elsässer, Radzik (ICALP 2014)

Core-periphery networks: *Distributed computing on core-periphery networks: Axiom-based design.* Avin, Borokhovich, Lotker, Peleg (Journal Of Parallel And Distributed Computing 2017)

Definition. The **volume** of a set of nodes $A \subseteq V$ in a graph is defined as $\text{vol}(A) = \sum_{v \in A} d_v$, where d_v is the degree of v .

Main Theorem

Theorem. Let $G = (V, E)$ be a graph where each node $v \in V$ is initially colored red and has degree $d_v \in \omega(\log n)$. Let $p \in [0, 1]$ be a constant. Then, if the nodes run a dynamics where in every round each node with probability p picks the color **blue** and with probability $1 - p$ runs the 2-choices dynamics, then there is a universal constant p^* such that

- **Almost-consensus:** If $p > p^*$, then the agents reach a configuration such that the **volume** of nodes supporting the **blue** color is $(1 - o(1))\text{vol}(V)$ within $\mathcal{O}(\log n)$ rounds with high probability.
- **Metastability:** If $p < p^*$, then the **volume** of the **blue** nodes never exceeds $\frac{1-3p}{4(1-p)}\text{vol}(V)$ for any $\text{poly}(n)$ number of rounds with high probability.

Proof idea.

- Give an upper and a lower bound on the expected number of red neighbors of any node $v \in V$ after one time step. Both can be expressed as a function whose behavior changes at p^* .
- If $p > p^*$, using a multiplicative form of the Chernoff bounds, show that the number of red neighbors of each node reduces by a constant with high probability. Using the union bound over the nodes, obtain the consensus result.
- If $p < p^*$, show with the same tools that for each node it is very unlikely that the number of red neighbors decreases in a round. Using the union bound over all nodes and a superpolynomial number of rounds, conclude the metastability result.

Corollaries

Corollary (Consensus). Consider a core-periphery network where each node has $\omega(\log n)$ neighbors. If c_r is large and $c_d > c^*$, then the nodes reach a configuration such that the **volume** of **blue** nodes is $(1 - o(1))\text{vol}(V)$ within $\mathcal{O}(\log n)$ rounds of the 2-Choices dynamics, w.h.p.

Corollary (Metastability). Consider a core-periphery network where each node has $\omega(\log n)$ neighbors. Then, with high probability, we have that for every round t and for any $\text{poly}(n)$ number of rounds of 2-Choices dynamics:

- if $c_r > \frac{1}{c^*}$, then $\text{vol}(B^{(t)}) \geq \frac{3}{4}\text{vol}(C)$
- if $c_d < c^*$, then $\text{vol}(R^{(t)}) \geq \frac{3}{4}\text{vol}(P)$

where $B^{(t)}$ are the **blue** agents and $R^{(t)}$ the **red** agents at time t .